

# **Uncertainty of low frequency sound attenuation estimate in marine sediment**

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## Objective:

- Measurement of marine sediment attenuation at frequencies lower than 5 kHz
- Evaluation of the uncertainty of the attenuation estimate

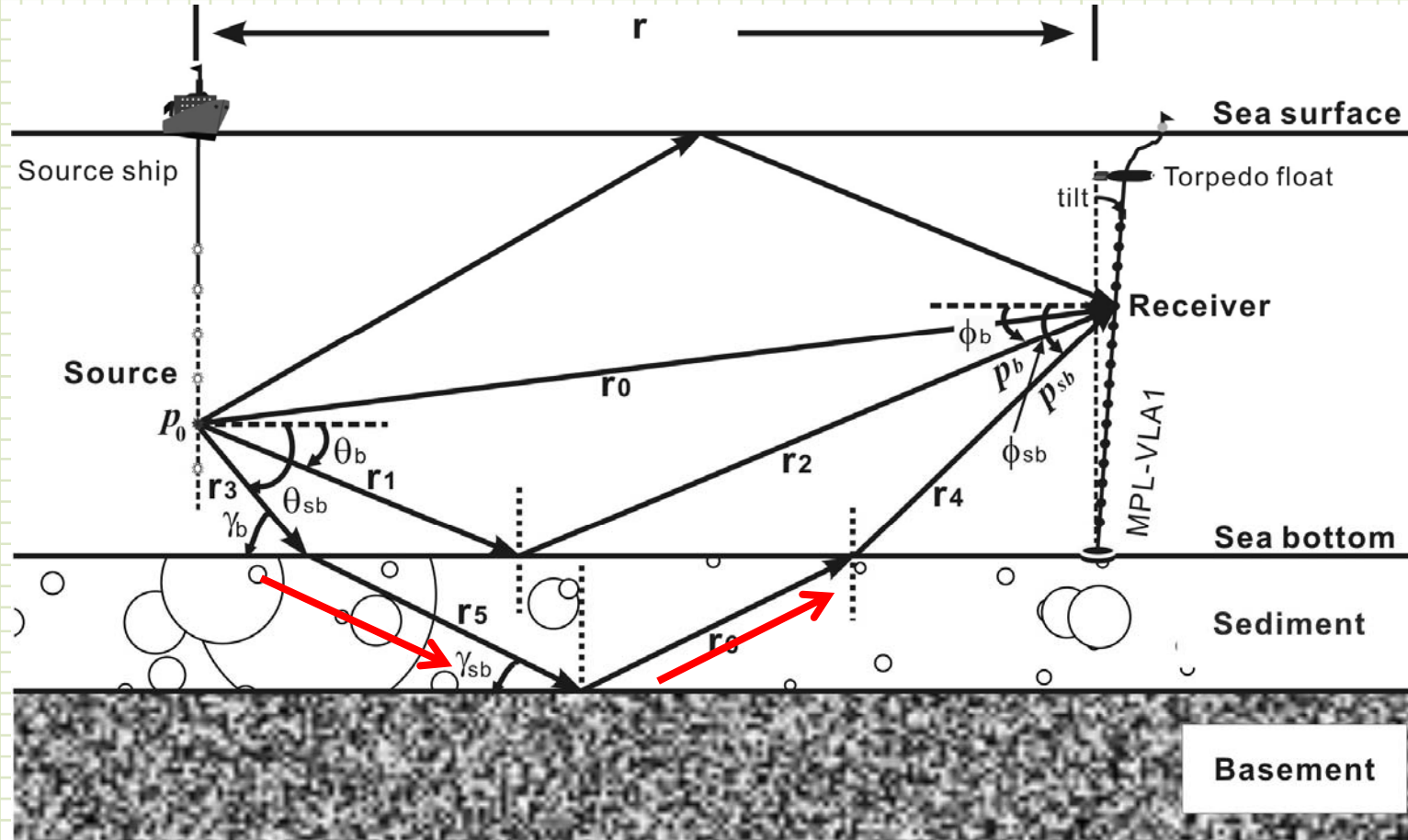
## Outline:

- Experimental geometry
- Sediment attenuation estimation method
- Factors that affect the uncertainty of attenuation estimates
  - fluctuation of the signals
  - uncertainties of sediment sound speed and layer thickness
- The results
- Summary and acknowledgements

# Methods of estimating sound attenuation in marine sediment :

- For attenuation at high frequencies ( $f > 10$  kHz):  
*In situ* measurements by using two embedded probes
- For attenuation at low frequencies ( $f < 1$  kHz):  
Inferences from different kinds of inversions of sound propagation data
- An alternate way of estimating the sediment attenuation:  
The signal used in this study is LFM pulse with frequency bandwidth of 1.5 kHz to 4.5 kHz

# Experimental geometry:



**Sound travel path in the sediment**



# Example of the received signal:

Direct arrival

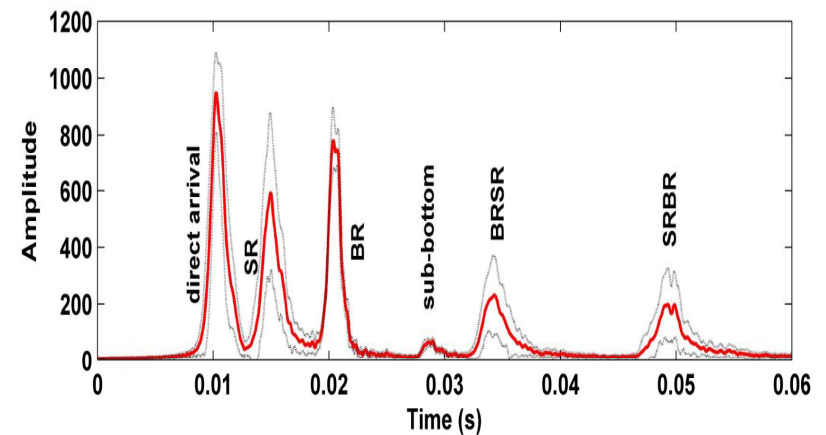
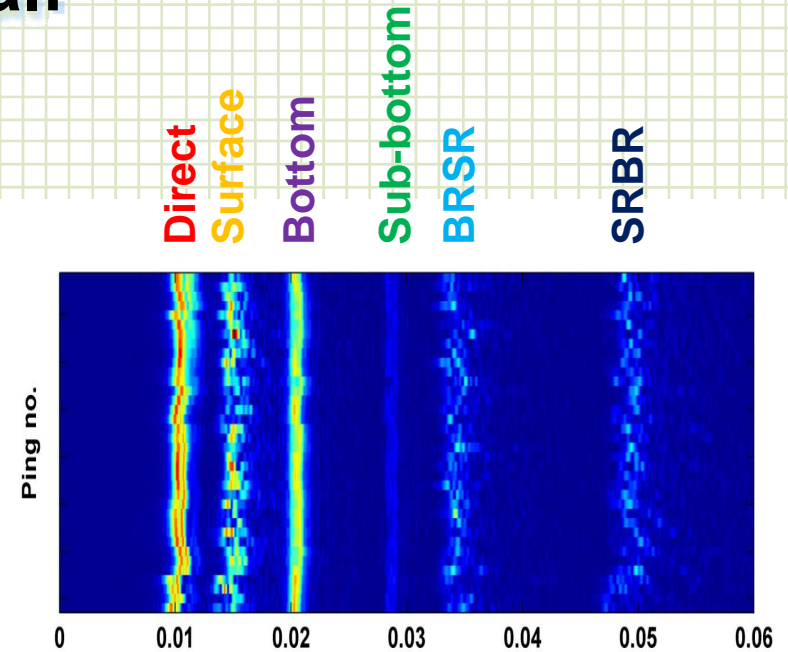
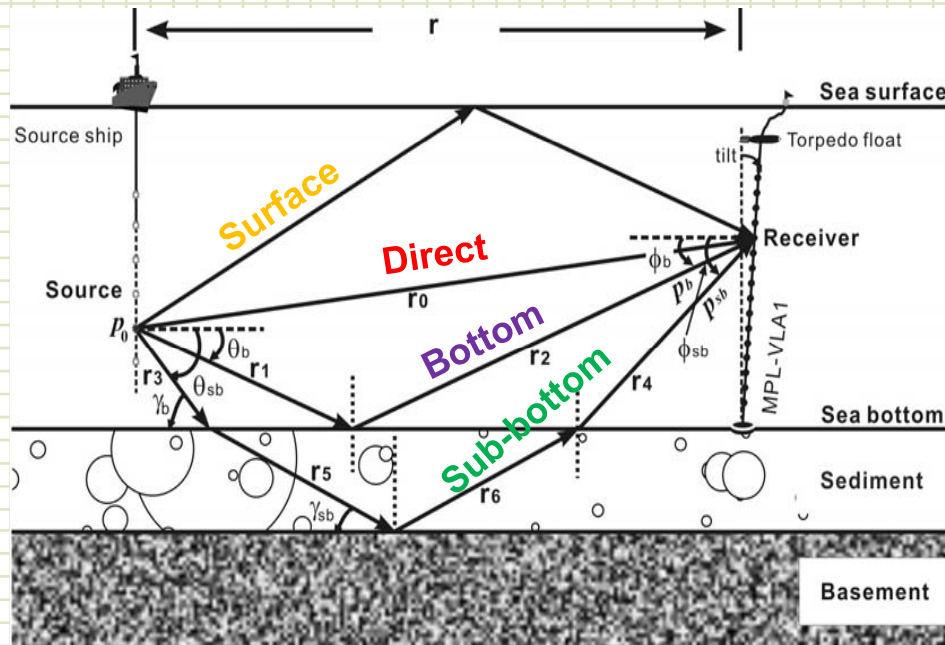
Surface reflection

Bottom reflection

Sub-bottom reflection

Bottom reflection surface reflection

Surface reflection bottom reflection



# Method of estimating sediment attenuation:

**Signal from bottom reflection:**

$$p_b(f) = \frac{p_0 V_b D^{Src}(f, \theta_b, \xi) D^{Rec}(f, \phi_b, \eta)}{r_1 + r_2} \cdot e^{-\alpha_w^{(neper)}(r_1 + r_2)}$$

$D^{Src}$  - Directional response of source

**Signal from sub bottom reflection:**

$$p_{sb}(f) = \frac{p_0 T_{ws} T_{sw} V_{sb} D^{Src}(f, \theta_{sb}, \xi) D^{Rec}(f, \phi_{sb}, \eta)}{r_3 + r_4 + r_5 + r_6} \cdot e^{-\alpha_w^{(neper)}(r_3 + r_4)} \cdot e^{-\alpha_{sb}^{(neper)}(f) \cdot (r_5 + r_6)}$$

$D^{Rec}$  - Directional response of receiver

**The ratio of reflections from bottom to sub bottom (dB):**

$$\Delta P(f) = 20 \log_{10} p_b(f) - 20 \log_{10} p_{sb}(f) = B + \alpha_{sb}(f) \cdot (r_5 + r_6)$$

**Linear frequency dependence:**

or

**Nonlinear frequency dependence:**

$$\Delta P(f) = (r_5 + r_6) \cdot \alpha_{sb}^{(f)} \cdot f + B$$

$$\Delta P(f) = (r_5 + r_6) \cdot \alpha_{sb}^{f_0} \cdot (f/f_0)^\beta + B$$

$\alpha_{sb}^{(f)}$  is in dB/m·kHz

$\alpha_{sb}^{f_0}$  is in dB/m @1 kHz,  $f_0$  is 1 kHz

$$\alpha_{sb}^{(\lambda)} = \alpha_{sb}^{(f)} \cdot c_{sb} / 1000 \quad \text{in dB}/\lambda$$

# The uncertainty of attenuation estimate:

Linear frequency dependence:

$$\Delta P(f) = (r_5 + r_6) \cdot \alpha_{sb}^{(f)} \cdot f + B$$

in dB/m·kHz

$$\Delta P(f) = \frac{1000 \cdot (r_5 + r_6)}{c_{sb}} \cdot \alpha_{sb}^{(\lambda)} \cdot f + B$$

in dB/λ

Nonlinear frequency dependence:

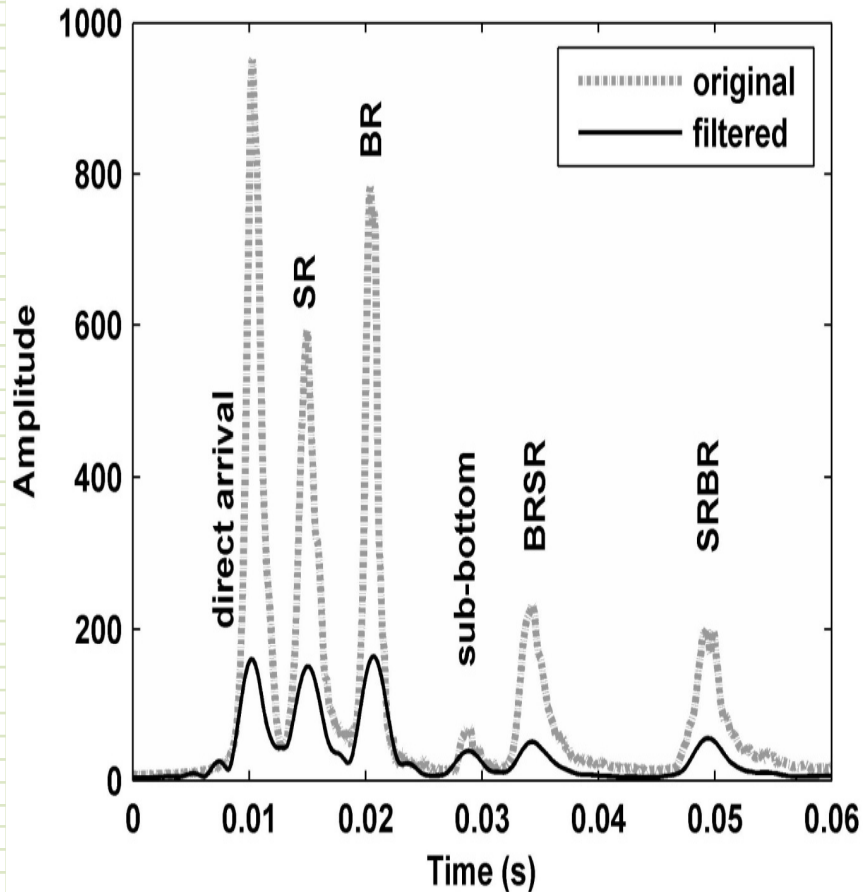
$$\Delta P(f) = (r_5 + r_6) \cdot \alpha_{sb}^{f_0} \cdot (f / f_0)^\beta + B$$

is in dB/m @1 kHz,  $f_0$  is 1 kHz

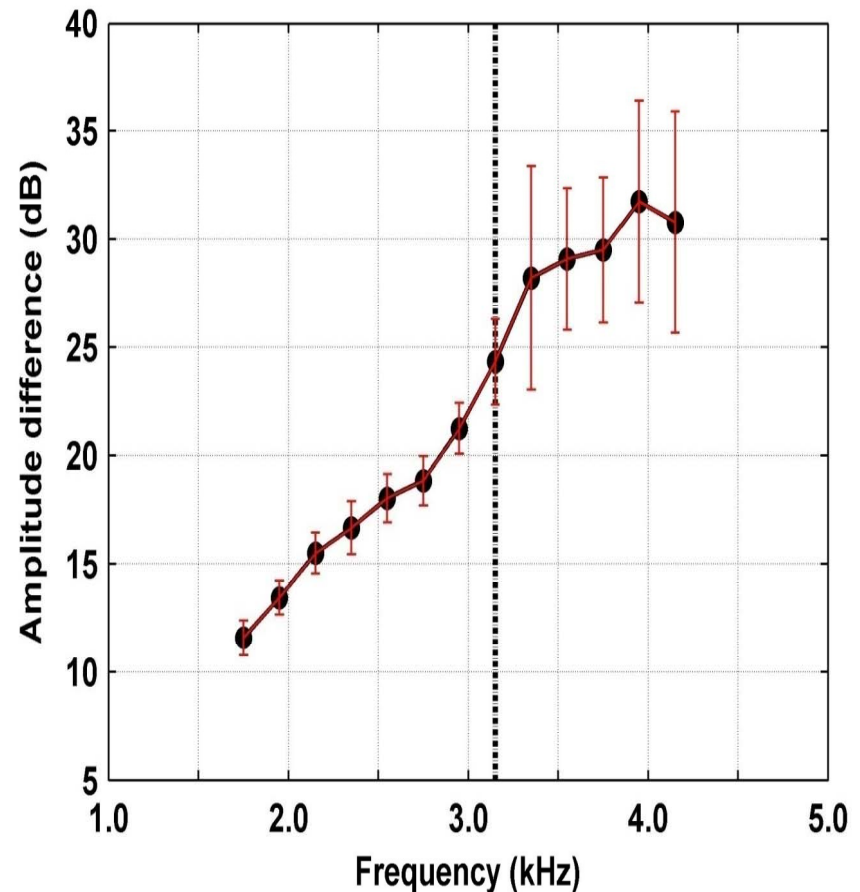
## The uncertainty of the attenuation estimate:

- ☐ the measurement
  - signal amplitude fluctuation
- ☐ the uncertainty of sound speed and layer thickness estimates
  - Bayesian travel time inversion

# Estimate attenuation from bottom and sub-bottom reflections:



Matched filtered waveforms



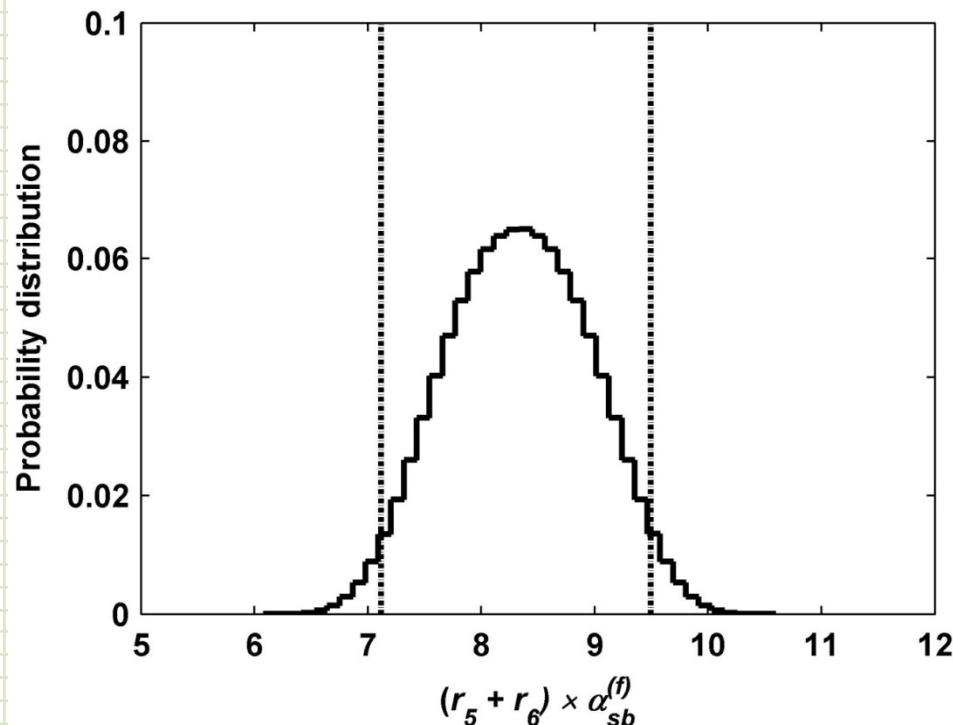
$\Delta P(f)$  at different frequencies



# Example of uncertainty due to signal fluctuation

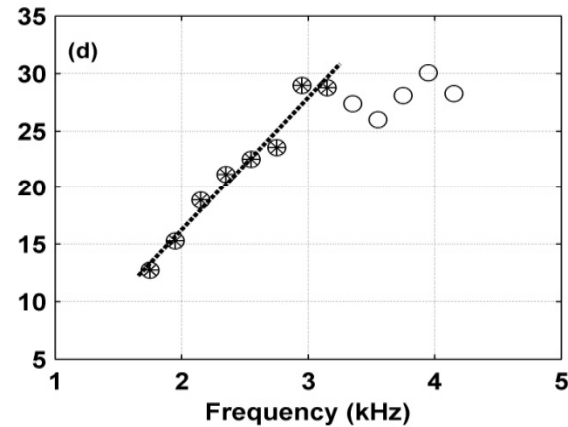
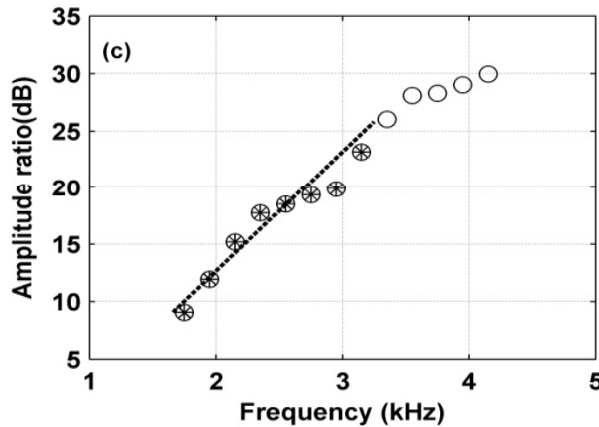
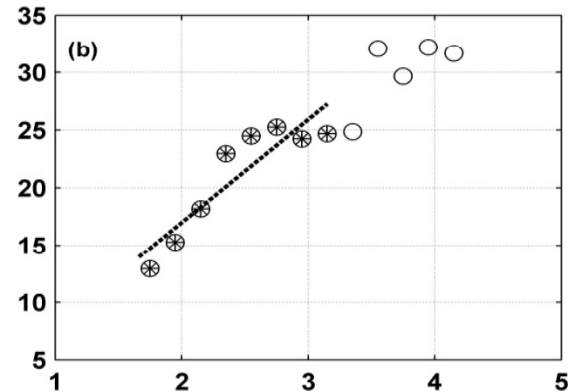
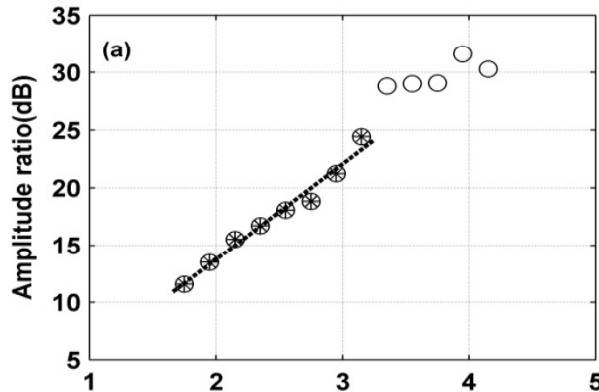
Determine the frequency dependence of the attenuation in terms of:

- the width of 95% of the credibility interval
- the consistency of the estimates from different source-receiver pairs

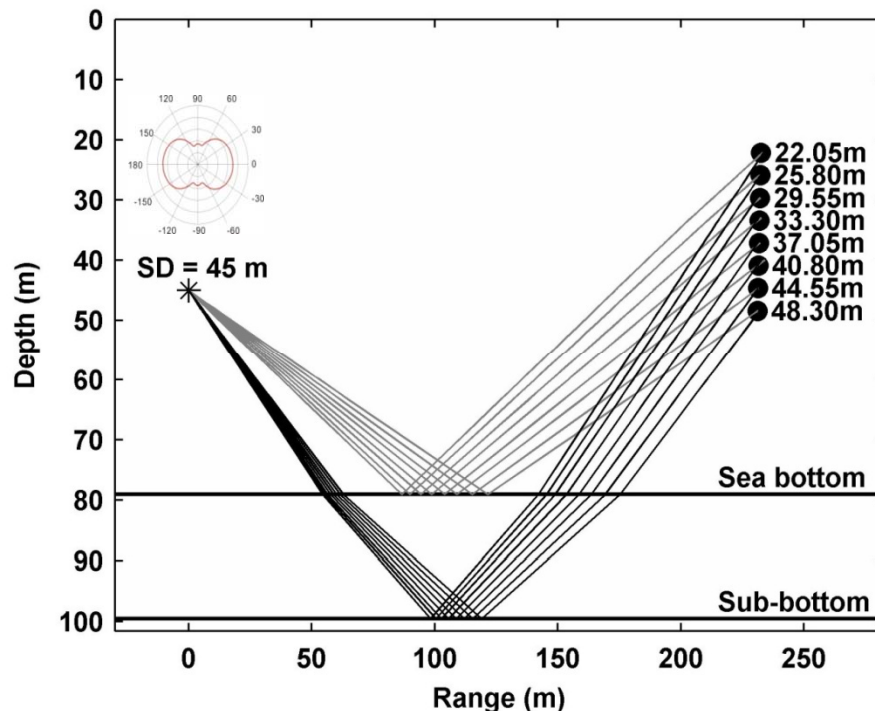


Monte Carlo approach,  
linear fitting

# Linear fitting for data from four source-receiver pairs



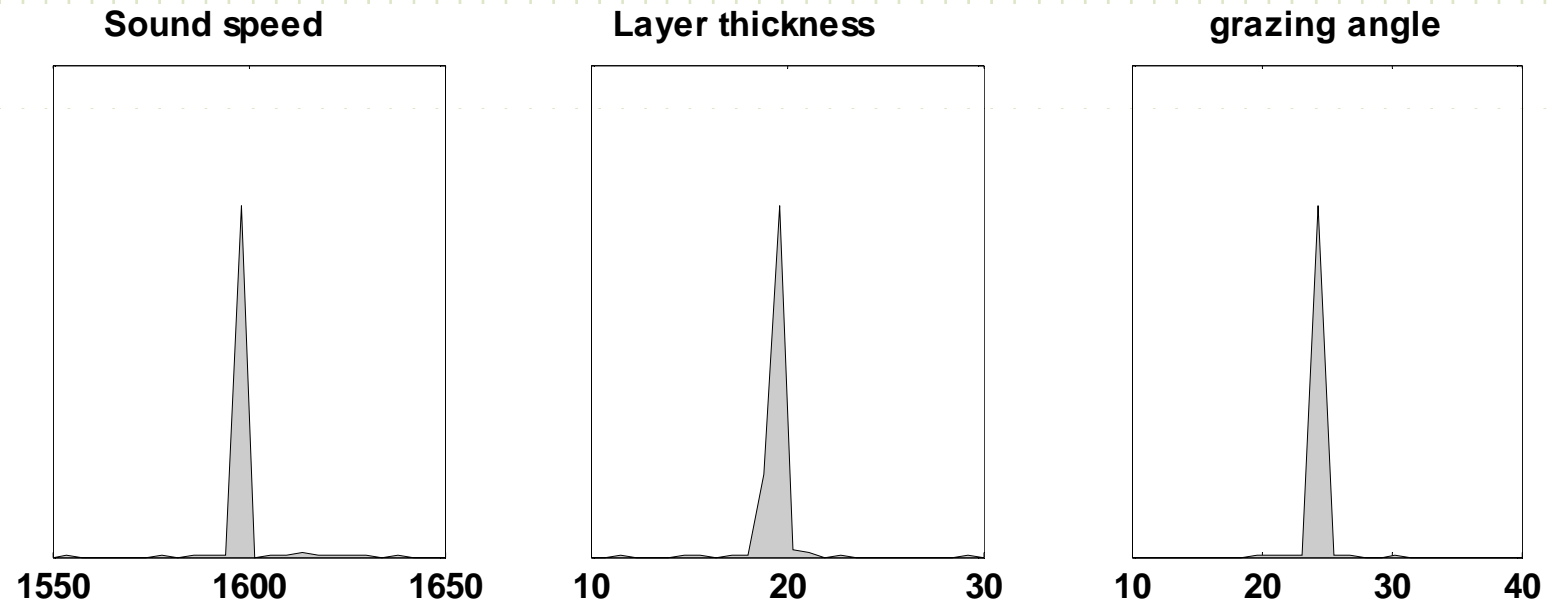
# The uncertainty of sediment sound speed and Layer thickness estimates:



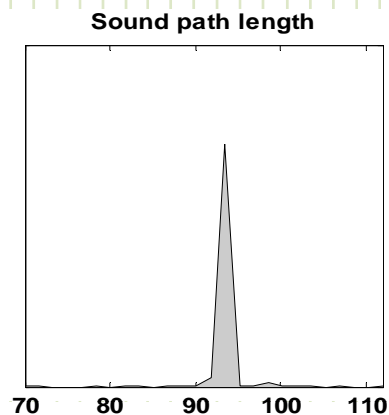
**Optimization:**  
Water column SSP,  
source & receiver geometry:  
Range, Water depth, Array tilt  
Source depth, Receiver depth

**Bayesian inversion:**  
Uncertainty of  
sediment sound speed  
and layer thickness

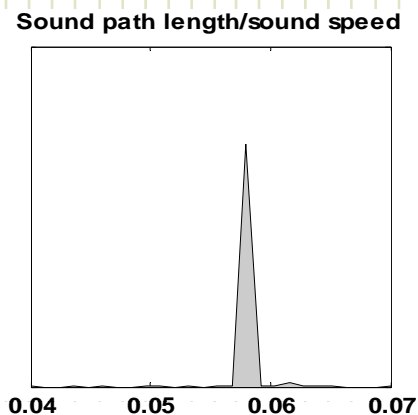
# Uncertainty of sediment sound speed and layer thickness estimates from Bayesian travel time inversion:



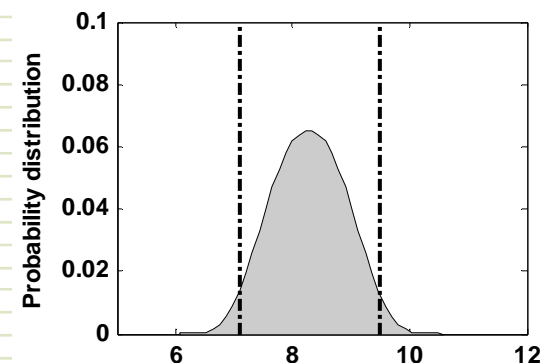
# Example of uncertainty of attenuation estimate:



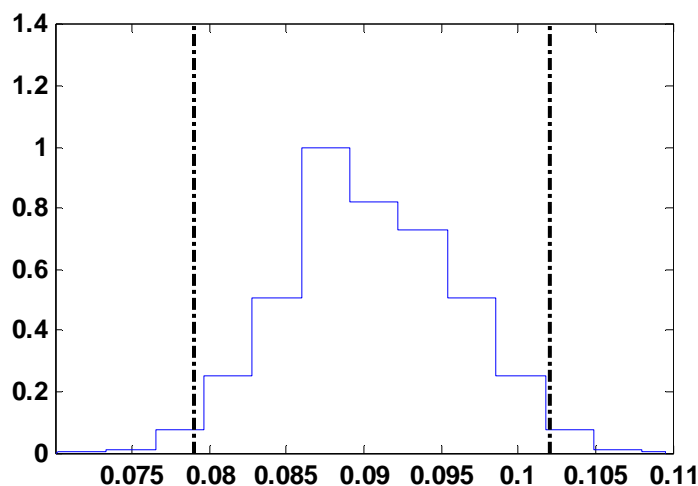
$$(r_5 + r_6)$$



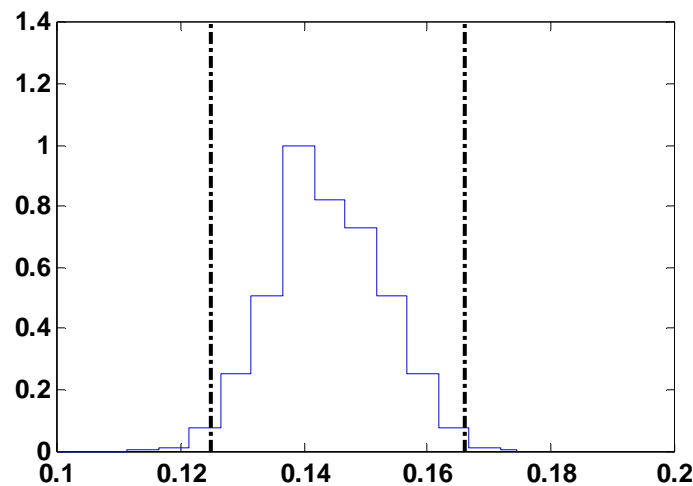
$$(r_5 + r_6) / c_{sb}$$



$$(r_5 + r_6) \cdot \alpha_{sb}^{(f)}$$



$$\alpha_{sb}^{(f)} \text{ in dB/m} \cdot \text{kHz}$$



$$\alpha_{sb}^{(\lambda)} \text{ in dB}/\lambda$$



# Summary:

- Marine sediment sound attenuation at low frequency is estimated from single bounce sub-bottom reflections
- Frequency dependence of the attenuation is determined by the measured data
- The uncertainty of the attenuation estimate is mapped from the fluctuation of measured signal and the uncertainty of the sediment property estimates from Bayesian travel time inversion
- VLA and source at different depths experimental geometry

# Acknowledgements:

- **Office of Naval Research:** for sponsoring the research
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