

# Effects of internal waves on acoustic coherent communications during SW06

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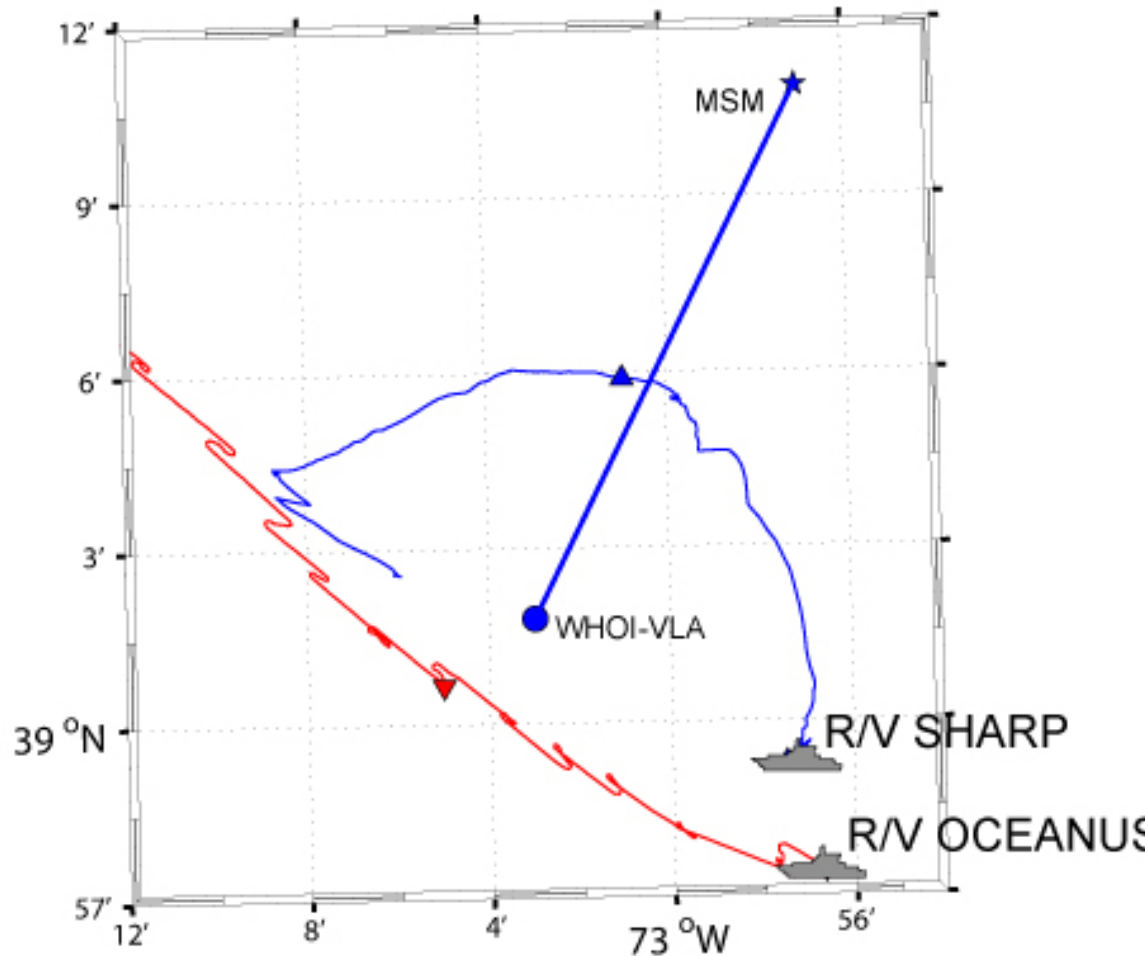
# Introduction

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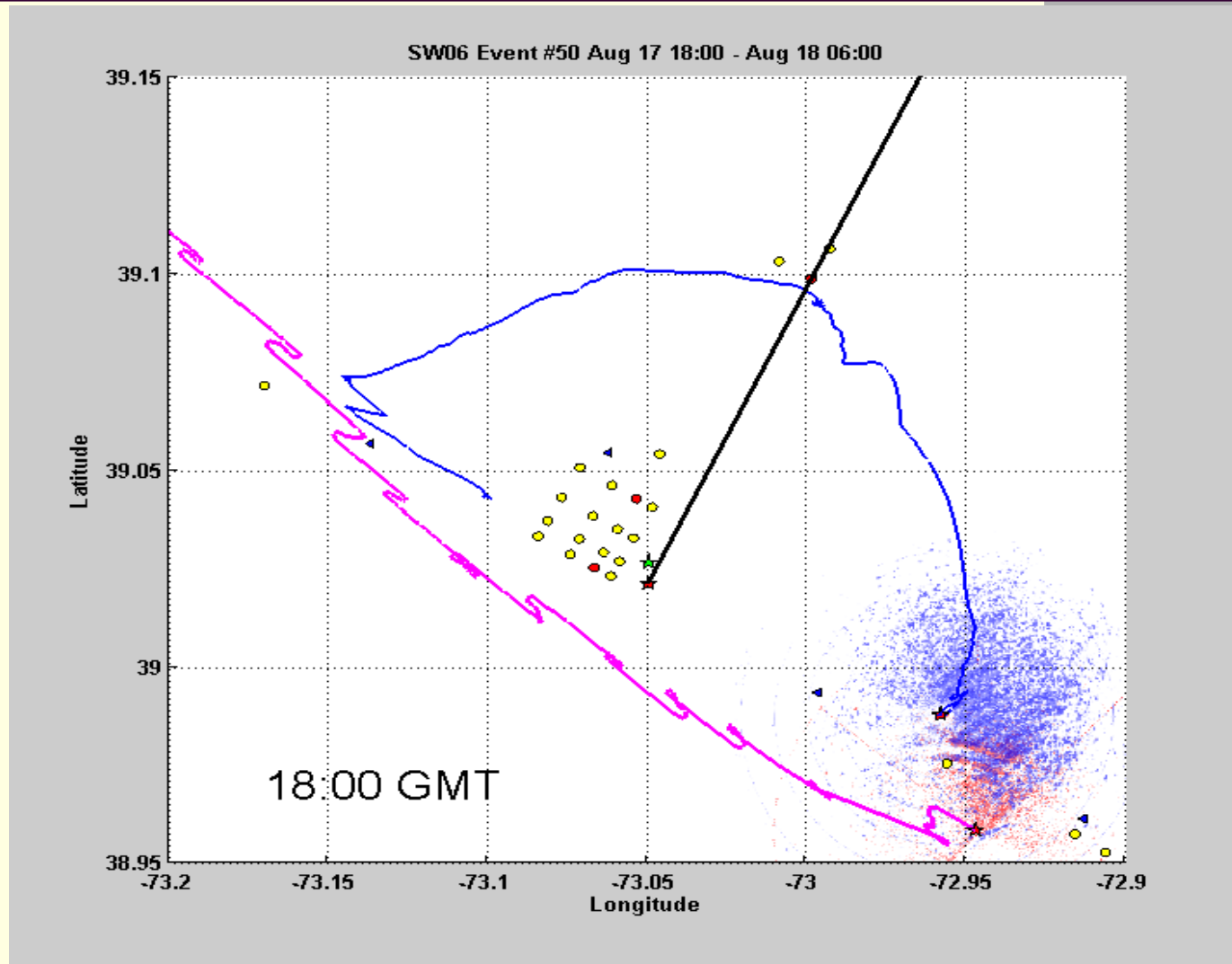
- Internal wave effects on acoustic signals (Apel, *et al.*, JOE1997)
  - Intensity fluctuation (Badiey, *et al.*, JASA2005, JASA2007)
  - Temporal coherency variation (Rouseff *et al.*, JASA2002, Yoo, JOE2005)
- Internal wave effects on underwater acoustic communications
  - Expected effects but limited results in the literature
  - Current efforts: 1) concurrent acoustic and environmental measurement; 2) using our time reversal based receiver, 3) the extent of the effects

# Experimental setting

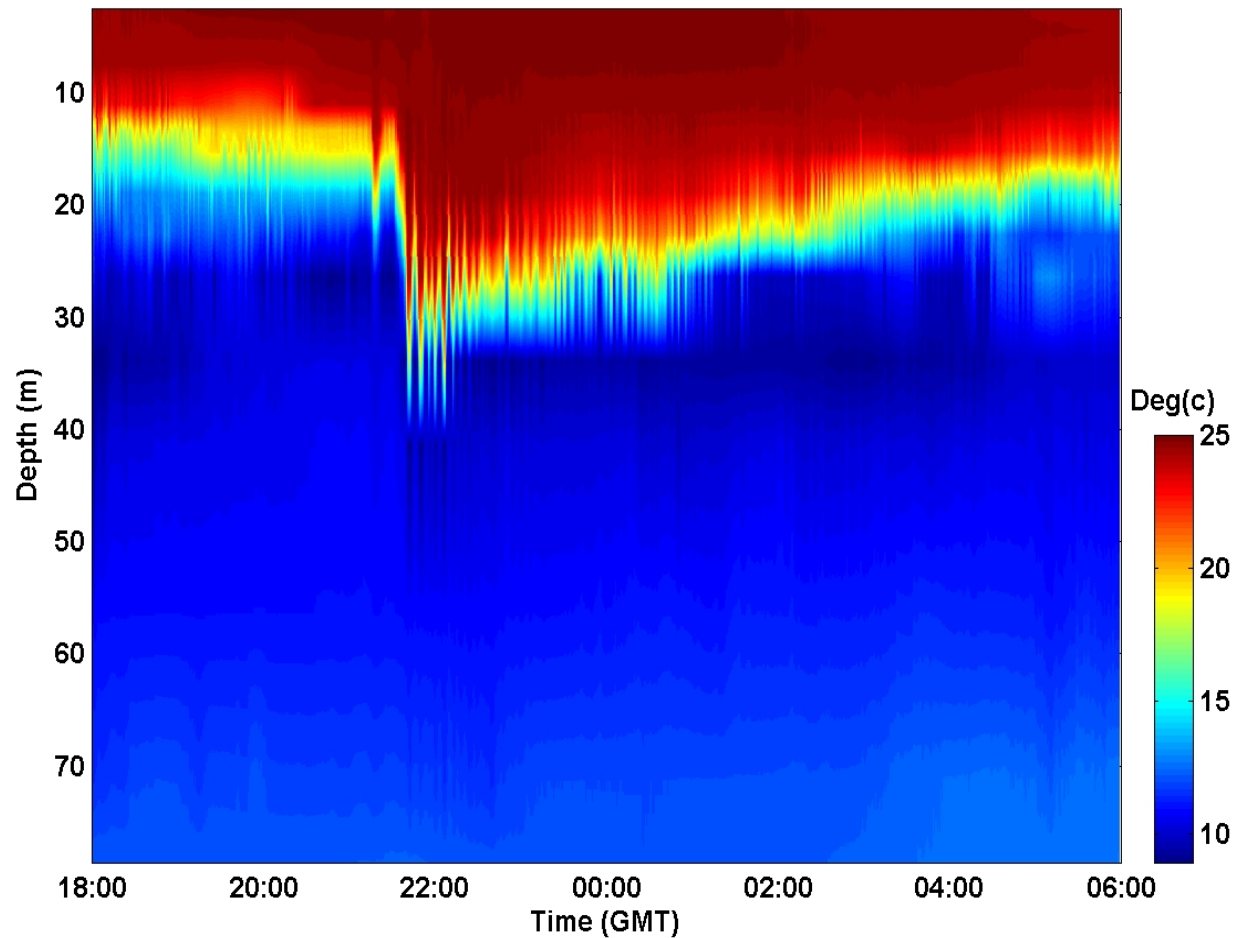
- Internal wave event # 50:  
18:00 (GMT) Aug 17 to  
06:00 Aug 18, 2006
- Source: MSM
- Receiver: WHOI-VLA
- Range: about 20 km
- Water depth: about 80 m
- Acoustic signal:  
~90 s M-sequences (BPSK  
signals) at carrier  
frequencies 813 Hz and  
1627 Hz
- Source level: 186 dB re 1  
micro Pa at 1 m
- Trans. Schedule: Every 30  
min



# Radar image



# Water temperature profiles



# Two environmental conditions

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- 18:00: Internal waves had not reached the acoustic track (about 10 km away from the acoustic track)
- 22:30: Internal waves overlap the acoustic track

# Receiver structure

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- At the source, the transmitted signal in the baseband form is:

$$x(t) = \sum_n x(n) g(t - nT)$$

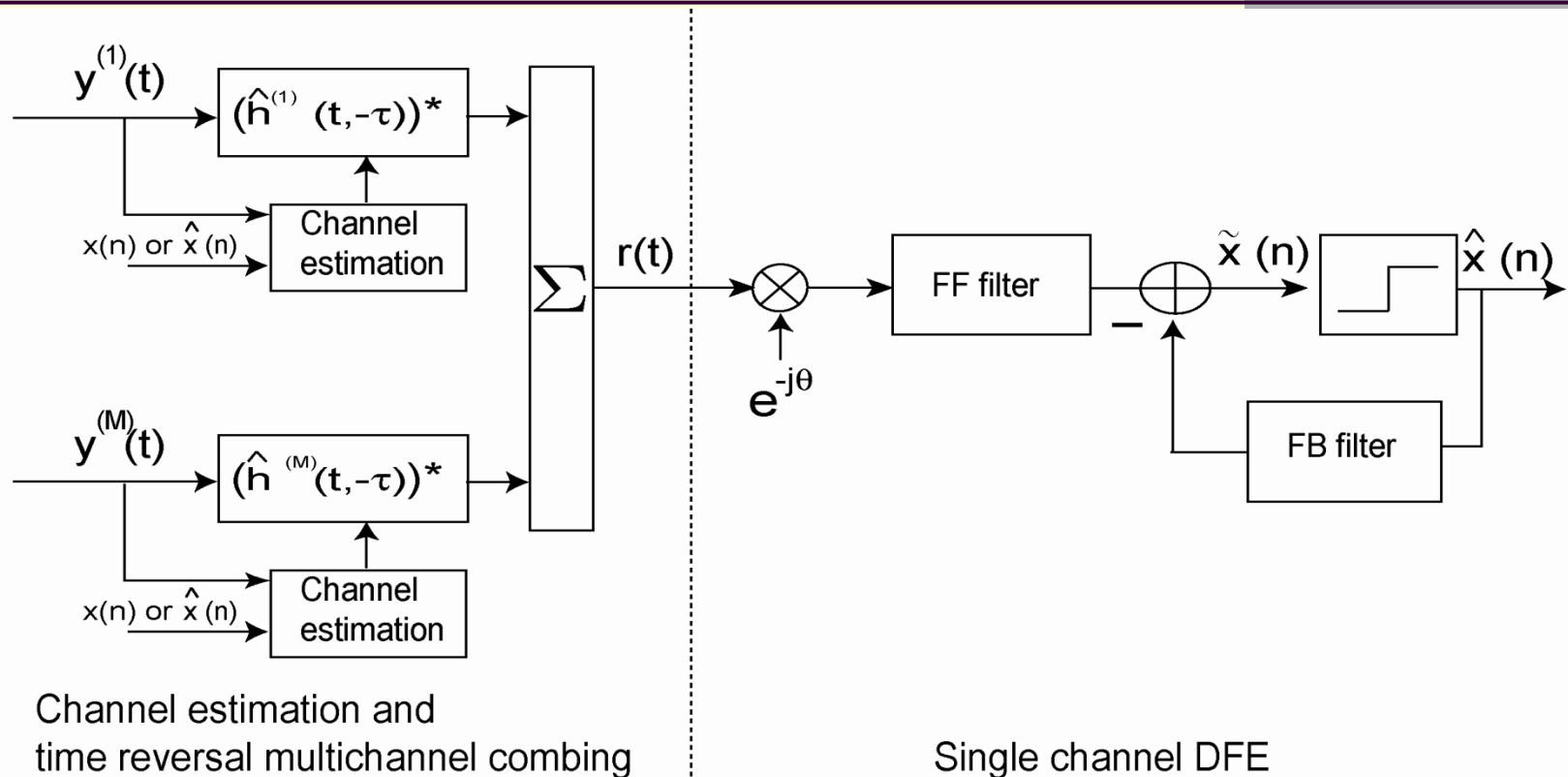
- The channel impulse response (CIR) function: dispersive (multipath), time varying

$$h^{(i)}(t, t')$$

- At the  $i$ -th element of the receiver:

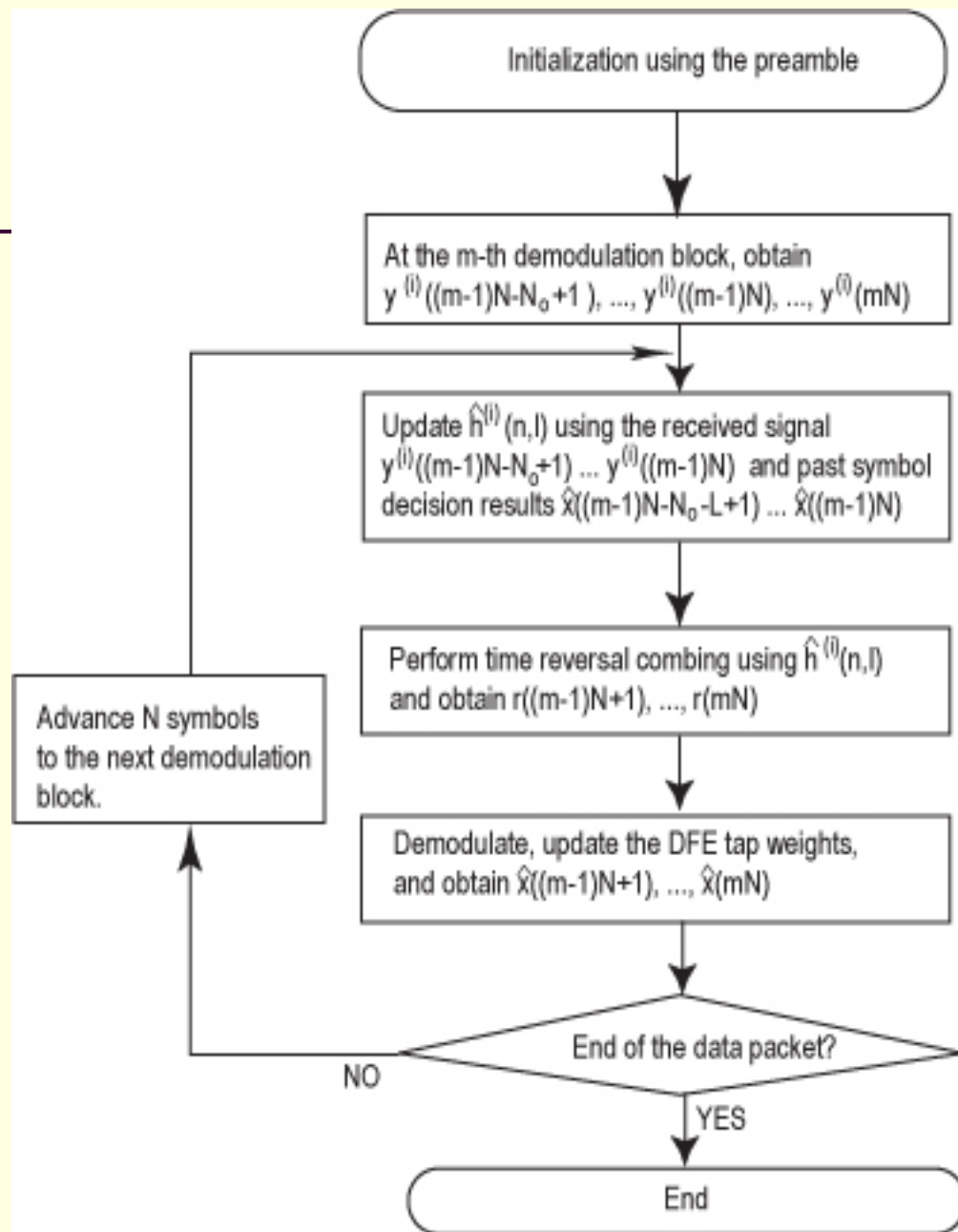
$$y^{(i)}(t) = x(t) * h^{(i)}(t, t') + v(t)$$

# Receiver structure



- Frequent channel estimation
- Soft output signal-to-noise ratio (SNR) of the decision-feedback equalizer (DFE) is the performance metric





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- Receiver design:
    - Presented in A. Song, M. Badiy, H.-C. Song, W. S. Hodgkiss, M. B. Porter and the KauaiEx group, JASA2008, but without Doppler correction
    - Can achieve robust high data rate communications under dynamic ocean environments
  - Comparison with other time reversal/DFE methods (Edelmann, *et al.*, JOE2005, T. C. Yang, JOE2005, H.-C. Song, *et al.*, JASA2006)
    - Frequent channel estimation

# Receiver parameters

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- Key parameter: channel update interval
- Choose channel update interval:
  - Depending on the fluctuating rate of the channel: Fast fluctuating channels require small channel update interval

# CIR function: 813 Hz

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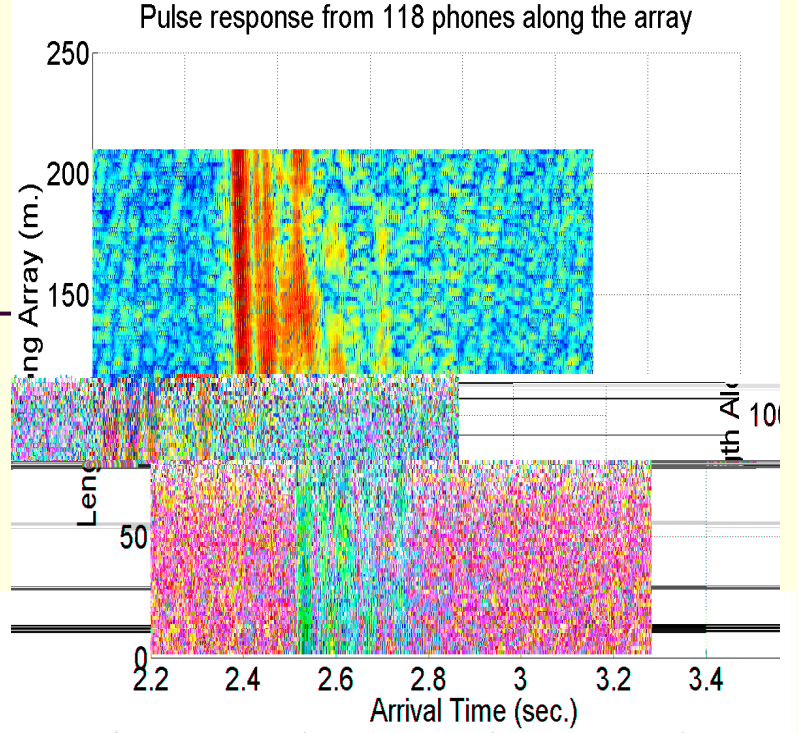
No internal waves(1800)

With internal waves(2230)

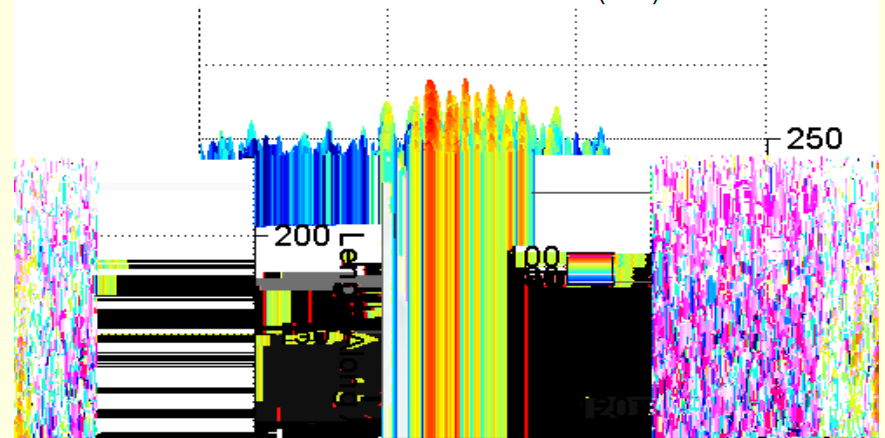
cir\_800hz



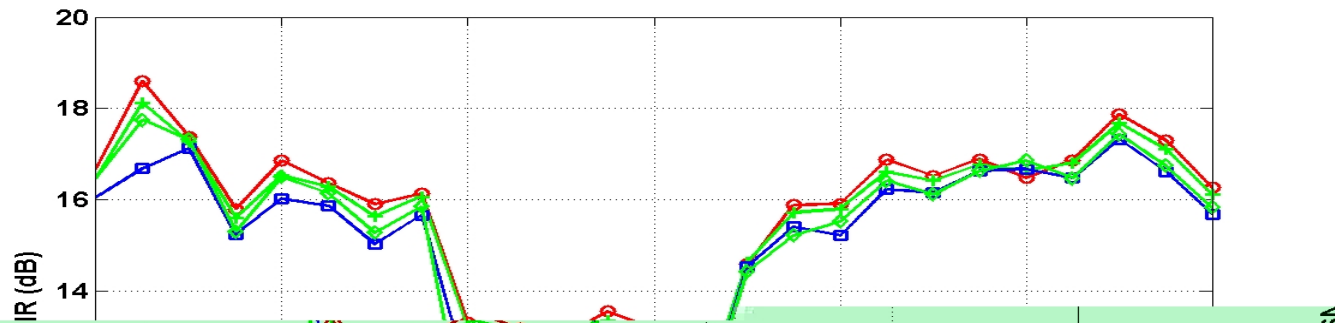
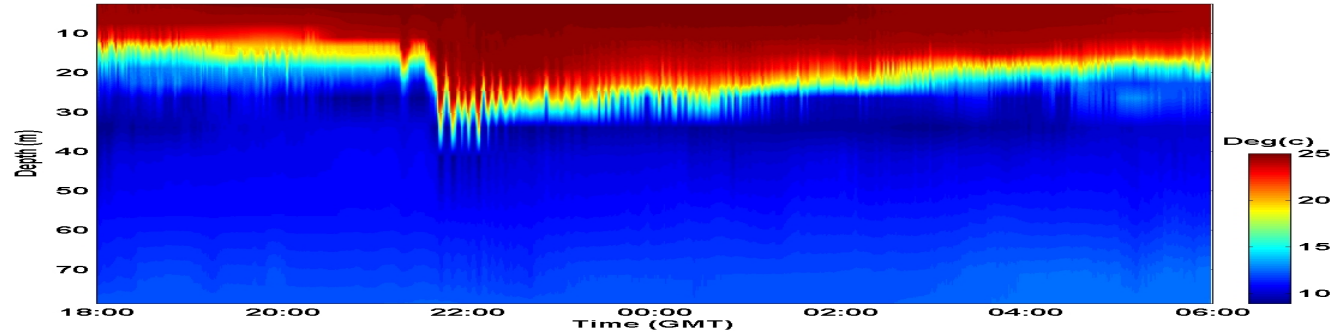
10 km



80 km



# Channel update interval for 813 Hz



12

Input SN

# CIR function: 1627 Hz

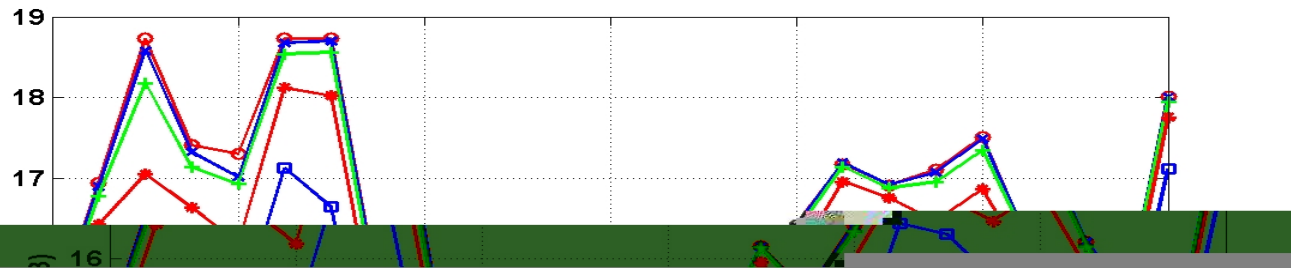
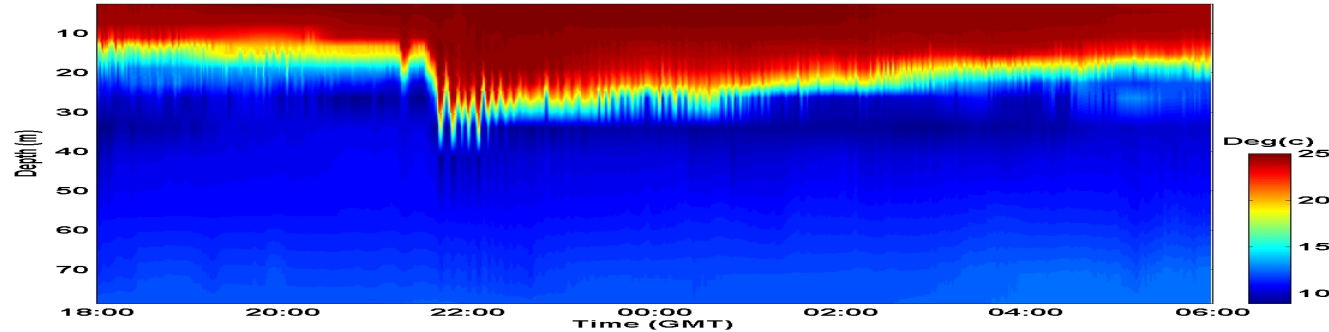
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No internal waves(1800)

With internal waves(2230)

cir\_1600hz

# Channel update interval for 1627 Hz

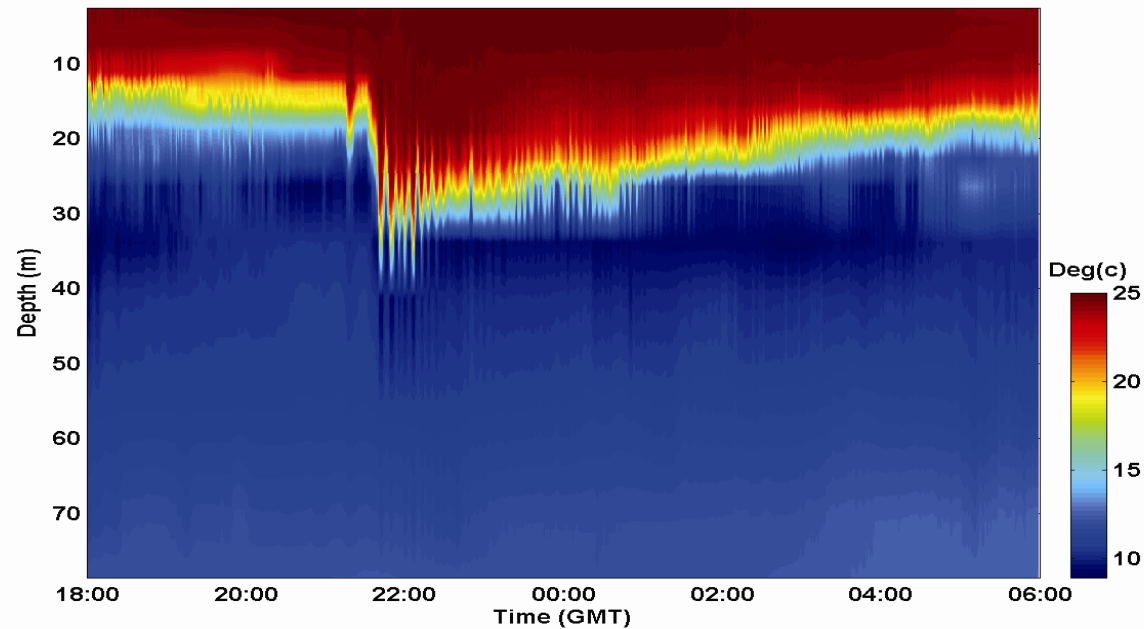




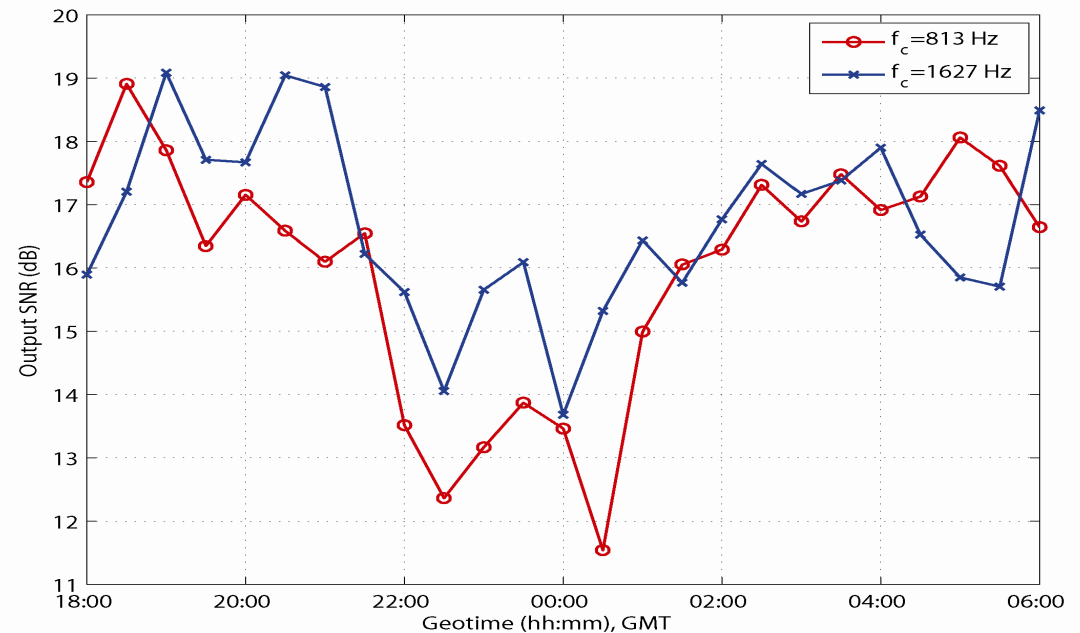
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- For 800 Hz carrier frequency:
    - Without internal waves, channel estimation can be performed every 8 s without loss of performance
    - With internal waves, channel estimation needs to be performed every 1 s
  - For 1627 Hz carrier frequency
    - Channel estimation needs to be performed every 250 ms regardless the internal wave condition

Channel  
update interval:  
250 ms

Frequency  
dependency



(a) Temperature profiles recorded at the WHOI-VLA



(b) The output SNR of the communications receiver

# Summary and future work

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- Concurrent acoustic measurements and environmental observations
- Significant internal wave effects on coherent underwater acoustic communications during a 12 h period at 813 Hz and 1627 Hz
- Receiver parameters can be depended on the environment condition and the carrier frequency
- Frequency dependency of the internal wave effects
  
- Acoustic modeling will be performed to explain the internal wave effects